

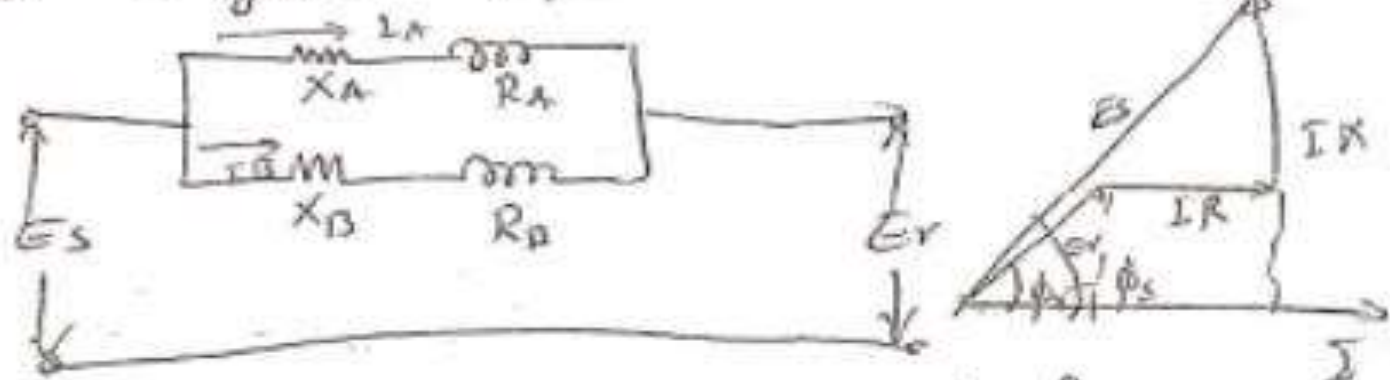
Lecture 8

Parallel Lines in Short Tx System

Parallel Lines

Sheet 50 Lines

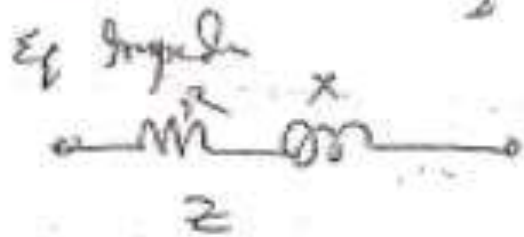
Two Problems - dealing with terminal conditions on 11 lines can be solved in exactly the same way as single line Problem on the assumption that the load current I now flows through an impedance $Z = R + jX$, where R is the joint resistance & X the joint reactance of the lines. If Z_A & Z_B represent the impedance of the lines and there is no dielectric interaction the joint impedance is



$$Z_A = R_A + jX_A$$

$$Z_B = R_B + jX_B$$

$$Z = \frac{Z_A Z_B}{Z_A + Z_B} \quad \parallel$$



$$Z = \frac{(R_A + jX_A)(R_B + jX_B)}{(R_A + R_B) + j(X_A + X_B)} * \frac{(R_A + R_B) - j(X_A + X_B)}{(R_A + R_B) - j(X_A + X_B)}$$

$$Z = \frac{R_A(R_B^2 + X_B^2) + R_B(R_A^2 + X_A^2)}{(R_A + R_B)^2 + (X_A + X_B)^2} + j \frac{X_A(R_B^2 + X_B^2) + X_B(R_A^2 + X_A^2)}{(R_A + R_B)^2 + (X_A + X_B)^2}$$

Impedance ^{drop} across A = Impedance ^{drop} across B = Impedance drop across eq. imped.

$$I_A Z_A = I_B Z_B = I Z$$

$$I_A Z_A = I Z \Rightarrow Z_A = \frac{I Z}{I_A} = I \left(\frac{Z_B}{Z_A + Z_B} \right)$$

Similarly $\Sigma_B = \frac{\Sigma_A}{\Sigma_A + \Sigma_B}$;

$\phi_V \rightarrow$ phase angle

$\Sigma \neq \Sigma_V$

Total Power $P_T = \Sigma_V L \cos \phi_V$

$\phi_A =$ phase angle Σ_A
 $\Sigma_A \neq \Sigma_V$.

$$\Sigma_V = \frac{P_T}{L \cos \phi_V}$$

$$P_A = \Sigma_A L \cos \phi_A$$

$$P_A = P_V \frac{\Sigma_A \cos \phi_A}{L \cos \phi_V} \quad \text{at P.f. } \cos \phi_A$$

$$P_B = P_V \frac{\Sigma_B \cos \phi_B}{L \cos \phi_V} \quad \text{at Power factor } \cos \phi_B$$

Short Type With Conditions Known at One End (II)

This is explained with the help of Example

A 20 mile. three phase line has the following constants

$$Y = 0.295 \Omega^{-1}, \quad X = 0.557 \Omega$$

At the receiving end, the voltage is 30 kV & the load, 2000 kVA (7200 kW at 0.9 p.f lagging). Determine the sending end conditions, the η & Regulation.

Solution

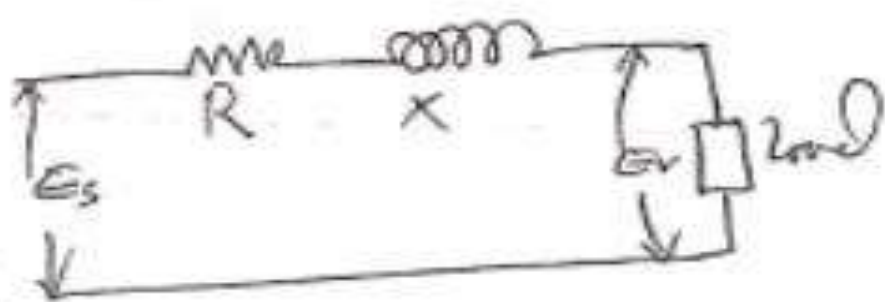
$$\text{Total Resistance } R = r \times l = 0.295 \times 20 = 5.9 \Omega$$

$$\text{Total Reactance } = X = x \times l = 0.557 \times 20 = 11.14 \Omega$$

Condition at Receiving end
 kVA per phase

$$(kVA)_{\text{phase}} = \frac{8000}{3} = 2667 \text{ kVA}$$

$$(kW)_{\text{phase}} = \frac{7200}{3} = 2400 \text{ kW}$$



$$E_{r(\text{line})} = \frac{30,000}{\sqrt{3}} = 17320 \text{ Volts} = 17.32 \text{ kV}$$

$$I = \frac{(kVA)_{\text{phase}}}{E_r} = \frac{2667}{17320} = 154 \text{ Amp}$$

$$IR = 154 \times 5.9 = 900 \text{ Volts}$$

$$\Sigma X = 154 \times 11.16 = 1715 \text{ Volts}$$

$$\cos \phi_r = 0.9 \Rightarrow \phi_r = \cos^{-1} 0.9 = 25.54^\circ$$

$$E_s = E_r \sqrt{(\cos \phi_r + IR/E_r)^2 + (\sin \phi_r + \frac{IX}{E_r})^2}$$

$$E_s = 17320 \sqrt{(0.9 + \frac{900}{17320})^2 + (0.436 + \frac{1715}{17320})^2}$$

$$E_s = 18.92 \text{ kV (to neutral)}$$

(12)

$$\& \phi_s = \tan^{-1} \frac{\sin \phi_r + IX/eV}{\cos \phi_r + IR/eV} \quad \text{putting values}$$

$$\phi_s = 29.32^\circ \quad \cos \phi_s = 0.872 \text{ lagging}$$

$$\text{Loss} = I^2 R = \frac{(154)^2 \times 590}{1000} = 140 \text{ kW}$$

$$\text{Efficiency} = \frac{P_{\text{output}}}{P_{\text{input}}} \times 100 = \frac{P_{\text{out put}}}{P_{\text{output}} + \text{Loss}} \times 100 = \left(\frac{2400}{2400 + 140} \right) \times 100$$

$$\eta = 94.5\%$$

$$(R_r = \frac{V_s - V_R}{V_R} \times 100)$$

$$\text{Regulation} = E_s - E_v = 18920 - 17320$$
$$R = 1600 \text{ V/V}$$

$$\% \text{ or Regult} = \frac{1600 \times 100}{17320} = 9.24\%$$

or can use the equation
desired.

$$\Rightarrow E_r^2 + E_r \frac{2I(R \cos \phi_r + X \sin \phi_r)}{u} + \frac{I^2(R^2 + X^2) - E_s^2}{v} = 0$$

We replace them term by u, v

We get $E_r^2 + u E_r + v = 0$

$$\boxed{ax^2 + bx + c = 0}$$

to get value E_r

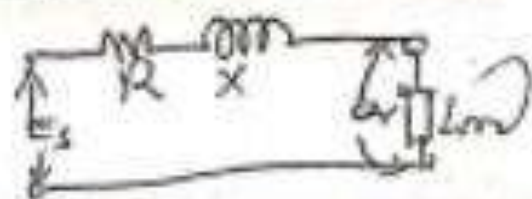
$$E_r = \frac{-u \pm \sqrt{u^2 - 4v}}{2}$$

high only the value chosen to get high E_r is efficient obtained.

Case-II P_r, E_s, ϕ_r are known

$P_r = E_r I \cos \phi_r$ is active power

$$I = \frac{P_r}{E_r \cos \phi_r} \dots \dots u$$



Reactive Power $Q_r = E_r I \sin \phi_r$ (kVAR)

$$I = \frac{Q_r}{E_r \sin \phi_r} \quad \text{--- II} \quad \text{putting value in equation of } \underline{E_s}$$

$$E_r^2 + E_r (2 I R \cos \phi_r + 2 I X \sin \phi_r) + I^2 (R^2 + X^2) - E_s^2 = 0$$

$$E_r^2 + 2 E_r \left[\frac{P_r}{E_r \cos \phi_r} R \cos \phi_r + \frac{Q_r}{E_r \sin \phi_r} X \sin \phi_r \right]$$

$$+ \left(\frac{P_r}{E_r \cos \phi_r} \right)^2 (X^2 + R^2) - E_s^2 = 0$$

$$\Rightarrow E_r^2 + 2 (P_r R + Q_r X) - E_s^2 + \left(\frac{P_r}{\cos \phi_r} \right)^2 \left(\frac{X^2 + R^2}{E_r^2} \right) = 0$$

Multiply both side by E_r^2

$$E_V^4 + E_V^2 [2(P_V R + Q_V X) - E_S^2] + \left(\frac{P_V}{\cos \phi_V}\right)^2 (X^2 + R^2) = 0$$

$$\text{Let } E_S^2 - 2(P_V R + Q_V X) = S$$

$$\left(\frac{P_V}{\cos \phi_V}\right)^2 (X^2 + R^2) = T$$

$$\Rightarrow (E_V^2)^2 - S E_V^2 + T = 0$$

Solution for E_V

$$E_V = \sqrt{\frac{S \pm \sqrt{S^2 - 4T}}{2}}$$

The solution giving the higher value of E_V and consequently the higher $P_x \eta$, is the one usually required and so the + sign should be used.